

1 **Synchronized asperities nucleate earthquakes on laboratory** 2 **faults**

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6 **ABSTRACT**

7 Abundant heterogeneity has been documented on faults in nature across a wide range of
8 length scales, including structural, mineralogical, and roughness variations. The role of complex
9 heterogeneity on fault mechanics and frictional stability is not well established and experiments
10 investigating heterogeneity have typically incorporated a single source of heterogeneity. Here,
11 we conduct rock friction experiments on rough, bimaterial creeping faults to explore the role of
12 lithological heterogeneity on fault mechanics and stability. When asperities juxtapose talc gouge,
13 stable sliding occurs with a low friction coefficient, μ . Encounters of strong diabase asperities on
14 rough, talc gouge-lined faults initiate dramatic increases in μ and transitions to unstable sliding
15 characterized by frequent stick-slip events, StSEs. Seismic moments and stress drops of StSEs
16 decrease as roughness increases. Intense mechanical damage limits the longevity of roughness
17 rendering fault-asperities mechanically insignificant after multiple encounters. Encounters of
18 strong, velocity weakening asperities provide a model to explain the nucleation of both seismic
19 and aseismic slip events on nominally stable, creeping faults.

20 **INTRODUCTION**

21 Faults are structurally complex in nature with abundant heterogeneity from the
22 microscopic scale up to the kilometer scale (Chester et al., 1993; Faulkner et al., 2003). Motion

23 or slip along a fault is regulated by frictional processes with some faults exhibiting both seismic
24 and aseismic slip (Miyazaki et al., 2011; Thomas et al., 2014; Avouac, 2015; Caballero et al.,
25 2021). Fault slip can be simplified to three mechanical states: a locked state where no slip occurs,
26 a stable sliding state dominated by slow slip, and an unstable sliding state dominated by fast slip.
27 Identifying factors that govern the transition between these states is key to advancing our
28 understanding of fast and slow earthquake mechanics and can inform other frictionally governed
29 geologic processes including landslides and glacial flow. Two potentially important factors relate
30 to sources of heterogeneity: roughness and mineralogy.

31 Fault roughness is well documented from the km- to μm -scale (Bistacchi et al., 2011;
32 Candela et al., 2012). Roughness is thought to regulate the distribution of stress on faults
33 (Candela et al., 2011; Fang and Dunham, 2013; Cattania and Segall, 2021). Kilometer scale
34 roughness has been linked to megathrust and shallow subduction zone earthquakes (Bilek and
35 Lay, 2002; Kirkpatrick et al., 2020), earthquake swarms (Cochran et al., 2023), and nucleation of
36 secondary rupture fronts (Xu et al., 2024). Large-scale roughness has also been suggested as a
37 mechanism to promote fault locking leading to earthquake nucleation (Lee et al., 2024). Though
38 there is consensus that roughness is mechanically important, the role of roughness on frictional
39 strength and stability is not clear. There are conflicting interpretations from laboratory
40 experiments on whether roughness promotes frictional instabilities (Eijsink et al., 2022; Goebel
41 et al., 2023) or inhibits them (Fryer et al., 2022; Xu et al., 2023). Other experimental
42 investigations document transitional stability regimes but with conflicting interpretations on
43 when roughness enhances or inhibits frictional instabilities (Harbord et al., 2017; Morad et al.,
44 2022).

45 Experiments investigating mineralogical heterogeneities often combine frictionally
46 strong, velocity weakening materials (μ decreases as velocity, V , increases) with frictionally
47 weak, velocity strengthening materials (μ increases as V increases). These investigations show
48 decreases in μ and increases in overall stability with increasing phyllosilicate content or when
49 fabrics are present (Crawford et al., 2008; Collettini et al., 2009; Tembe et al., 2010; Moore and
50 Lockner, 2011; Tesei et al., 2014; Hirauchi et al., 2023). More complex faults with distinct
51 heterogeneous patches show decreased frictional stability on bimaterial faults compared to
52 homogeneous faults (Bedford et al., 2022). In other experiments, long-term strengthening was
53 documented and attributed to mixing of bimaterial patches (Arts et al., 2024).

54 As natural faults exhibit abundant heterogeneity, experiments that incorporate complex,
55 multi-source heterogeneity can advance descriptions of fault mechanics and scaling of results
56 from the lab to nature. We investigated the frictional properties of rough, bimaterial laboratory
57 faults to explore the role of complex heterogeneity on frictional stability. The sliding surfaces of
58 our experimental faults were engineered to facilitate direct links between slip-dependent
59 mechanical behaviors and geometries of rough surfaces. To our knowledge, these are the first
60 experiments to incorporate roughness and mineralogical heterogeneity simultaneously. We
61 present mechanical and microstructural data from experiments and explore stability in the
62 context of complex heterogeneity. Ultimately, we present a framework for transitions from stable
63 to unstable sliding during fault creep that could nucleate seismic and aseismic slip events in
64 nature including earthquakes, low frequency earthquakes, slow slip events, and tremor.

65 **EXPERIMENTS**

66 Experiments were performed using the Tullis Rotary Shear Apparatus¹ at Brown
67 University at 25 MPa confining stress, 30 MPa normal stress, room temperature, and room

68 humidity. We prepared annular samples of Frederick diabase with macroscopic asperities (Figure
69 1). The diabase is velocity weakening with a μ of 0.75 at the normal stress of our experiments.
70 Between asperities, we packed a velocity strengthening talc gouge with a μ of 0.1. Coupling a
71 talc gouge with the rough diabase has two benefits. Once at high normal stress, the gouge
72 compacts relative to the initial sample geometry of Figure 1C, forcing asperities to ride over one
73 another during encounters and allowing us to explore the role of roughness and mineralogy
74 simultaneously. The contrasting mechanical behavior also allows us to distinguish the
75 mechanical effects of each material.

76 To vary roughness, we used four geometries with amplitude to wavelength roughness
77 ratios, R , of 0.007-0.003, representing the higher end of natural fault R that ranges from 0.01-
78 0.0001 (Power and Tullis, 1991). We calculate R using asperity height divided by the
79 circumferential length of an asperity and the clockwise gap before the next asperity and report
80 the average for all lower sample asperities (Figure 1C). Experiments were conducted with
81 symmetric roughness, R_S , or asymmetric roughness, R_A . In R_S experiments, the upper samples
82 included seven symmetric asperities while the lower samples hosted seven, five or three
83 asperities corresponding to average R_S of 0.007, 0.005 or 0.003. While the number of asperities
84 decreased, the locations remained uniform ensuring all asperities enter and exit contact
85 synchronously and lifetimes of asperity contacts are constant between all geometries (Figure 1B
86 and 1C). This synchronicity and symmetry of asperities simplifies the identification of
87 mechanical effects of roughness. For the R_A experiment, asperity locations were randomly
88 permuted within 50° regions while maintaining an average R_A of 0.007. To isolate the
89 mechanical effects of synchronizing asperities, and to limit velocity-dependent changes in wear
90 rates (Boneh et al., 2013), a constant sliding velocity of $5 \mu\text{m/s}$ was maintained in all but one

91 experiment. Experiments were conducted with total displacements, d , of 30 to 170 mm, allowing
92 1.5 to 7 asperity encounters, respectively.

93 **RESULTS**

94 When asperities interact on rough surfaces, rapid increases in μ trigger a shift from stable
95 to unstable sliding with roughness controlling the peak μ and StSE characteristics (Figure 2).
96 Stable sliding with a low μ dominated the first five mm of slip for all experiments when there
97 was no diabase-diabase contact (Figure 2C). As the asperity mating index approached 1,
98 representing fully mated asperities, μ increased, approaching diabase friction, and the fault
99 transitioned from stable to unstable sliding characterized by frequent StSEs. The peak μ ranged
100 from 0.78 to 0.6, decreasing with R_S . The increase in μ coincided with dilation at the sliding
101 surface, with the magnitude of dilation increasing at higher R_S . As asperities unmated, μ
102 decreased approaching the initial value and stable sliding resumed. This history repeated during a
103 second asperity lifetime, though the μ peaks were reduced. Following the second lifetime, there
104 was no significant change in μ with d or asperity mating index. Quasi-stable sliding was
105 maintained for the remainder of slip with occasional instabilities at d up to 150 mm; μ always
106 exceeded talc μ in all experiments. The amplitude of dilational events related to mating asperities
107 decreased with d and decreasing R_S . By the seventh asperity lifetime, the amplitude of dilation
108 during asperity encounters was significantly diminished.

109 StSEs occurred in all geometries, predominately during the first two asperity lifetimes
110 (Figure 2A). When R_S was low, StSEs were most frequent as the asperity mating index increased
111 and asperities entered contact. With larger R_S , StSEs were more frequent while the asperity
112 mating index decreased (Figure 2D).

113 Representative microstructures from four experiments are shown in Figure 3.
114 Pulverization and smoothing of the trailing and leading asperity edges was observed in all
115 experiments. In low R_S experiments (Figures 3A and 3C), extensive, penetrating fracturing and
116 pulverization occurred behind the asperity leading edges, with these regions elongating and
117 connecting on one of the sample blocks. No widespread fracturing or pulverization was observed
118 in high R_S experiments (Figures 3B and 3D). The overall degree of fracturing and pulverization
119 did not vary significantly between low and high d experiments in either geometry.

120 **DISCUSSION**

121 When asperities interact on rough, bimaterial faults, the mechanical behavior of the fault
122 reflects the mineralogy and abundance of asperities; outside of asperity encounters, the
123 mechanical behavior is an intermediate between the two materials. In our experiments, talc
124 comprises 71-80% of the sliding surface while diabase comprises 29-20% of the sliding surface.
125 If μ is calculated using $\mu = \mu_{talc}P_{talc} + \mu_{diabase}P_{diabase}$ where P is the area percent, we would expect
126 values of 0.29 to 0.23, averaging at 0.26. Instead, during the first asperity lifetime when diabase
127 juxtaposed diabase (strong-strong contacts) μ increased dramatically approaching bare diabase
128 values, though strong-strong contact area was only 29-12% of the sliding surface.

129 After the first asperity lifetime, μ decreased approaching the estimated aggregate
130 estimates. Dramatic, though reduced, increases in μ occurred again during the second contact
131 lifetime. The reduction in μ likely reflects a combination of mechanical damage that occurred
132 during the first lifetime and smearing of talc along asperity surfaces. After this second lifetime, μ
133 values remain low for the duration of sliding, reflecting intense mechanical damage during the
134 first two lifetimes rendering asperities mechanically insignificant (Figure 3). In low R_S
135 experiments, long-term μ is consistent with aggregate estimates. For the high R_S experiment,

136 long-term μ was 0.5, exceeding the aggregate estimate of 0.29. This likely reflects mixing of
137 pulverized diabase into the talc gouge due to the extensive damage at trailing and leading edges
138 of asperities (Figure 3). Though more fracturing and pulverization occurs in lower R_S
139 experiments, there are fewer asperities and upper sample asperities experience extended periods
140 of no contact likely resulting in less mixing and a lower μ .

141 We calculated the seismic moment M_0 and cumulative moment for StSEs using $M_0 =$
142 $GA d_e$ where G is the rigidity or shear modulus, A is the sliding surface area, and d_e is the StSE d .
143 StSEs are defined as drops in μ of 0.005 or more during 0.5 μm of d . We used a G of 24 GPa,
144 calculated from a proportional average of the values of G of 22 GPa for talc (Bailey and
145 Holloway, 2000) and 30 GPa for diabase (Weijermars, 1997), an A of 729 mm^2 based on the
146 sample dimensions assuming the entire interface slips when instabilities occur, and measured d
147 for d_e . We also measured the shear stress drop, $\Delta\tau$, during StSEs.

148 Seismic moment and stress drop both increase with decreasing R_S , suggesting roughness
149 increases stability (Figure 4). StSEs presumably reflect cataclastic failure at critically stressed
150 microscopic asperity contacts located on strong-strong contacts. Inhomogeneous normal stress
151 distributions have been documented in experiments on granite (Barbery et al., 2023). Since
152 decreasing roughness lowers the total strong-strong contact area, if stresses are localized on
153 strong-strong asperities, decreasing roughness increases the stress concentration at each strong-
154 strong contact. These larger normal and shear stresses at microscopic asperities prior to failure
155 would explain larger stress drops and seismic moments with lower roughness, since critical
156 stiffness increases with normal stress. With reduced strong-strong contact area there may also be
157 fewer asperities to serve as barriers to arrest or slow slip when asperities fail.

158 Concentrated stresses could also explain the different timing of StSEs. With larger R_S ,
159 increased strong-strong contact area may result in sufficiently distributed initial stresses
160 preventing early StSEs. As illustrated in Fig 2D, microscopic asperities tend to fail as strong-
161 strong contact area is reduced during unmating. In contrast, when R_S is low and strong-strong
162 contact area is reduced, StSEs are more prevalent as asperities enter contact, suggesting stresses
163 are sufficiently concentrated to induce failure. Mechanical damage due to early StSEs may
164 alleviate stress concentrations during unmating and explain why instabilities do not recommence.
165 The late StSEs in experiment 404 (Figure 4A) likely reflect a lack of mechanical damage; in this
166 experiment asperities were initially mated with no mechanical damage prior to unmating and
167 StSEs began as the mating index neared 0.

168 Cumulative moment was smaller for high R_S , and similar for intermediate to low R_S
169 (Figure 4A) reflecting a balance between roughness magnitude and asperity longevity. When
170 roughness is high, stress is sufficiently distributed to minimize damage and instabilities resulting
171 in low cumulative moments and occasional StSEs after the first encounter. With intermediate to
172 low roughness, stress is more localized resulting in numerous instabilities during the first 2-3
173 encounters, after which StSE frequency, M_0 and $\Delta\tau$ decrease. The maximum cumulative moment
174 occurred in the asymmetric experiment and likely reflects a similar balance between magnitude
175 and longevity of roughness enhanced by the complex asperity mating history during sliding.

176 This work demonstrates the complex mechanical behavior of heterogeneous faults. When
177 frictionally stable, weak materials juxtapose strong or weak materials, stable sliding dominates.
178 When frictionally strong asperities interact, the mechanical behavior alters dramatically,
179 approaching the frictional behavior of the strong asperities. The average, peak μ decreased as R_S
180 decreased. Assuming the peak μ is a function of the peak diabase μ of 0.79, and that changes in

181 observed μ reflect changes in normal stress at asperities, this observation suggests normal stress
182 increases by 120% and 140% as R_S decreases, in overall agreement with the decreased dilation
183 and increased damage observed with decreasing R_S . Encounters of strong, velocity weakening
184 asperities may promote the nucleation of seismic and aseismic events on nominally creeping
185 faults. Whether failure occurs seismically or aseismically may depend on the size and rheology
186 of asperities, with larger asperities nucleating earthquakes and smaller asperities nucleating slow
187 slip or tremor. Similar processes may also contribute to landslide initiation. While synchronized
188 strong-strong asperities can initiate rapid and dramatic transitions from stable to unstable sliding,
189 asperities undergo extensive damage during encounters and become mechanically obsolete
190 following multiple interactions.

191 **ACKNOWLEDGEMENTS**

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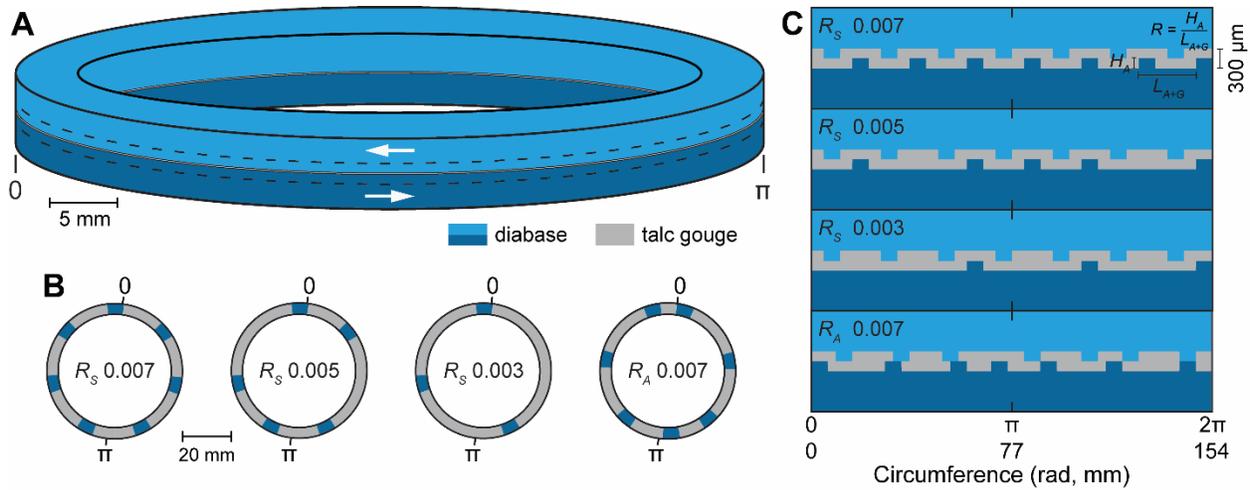
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302 **FIGURES AND CAPTIONS**



303

304 **Figure 1.** Initial sample geometries. A) Schematic view of annular samples showing the sense of

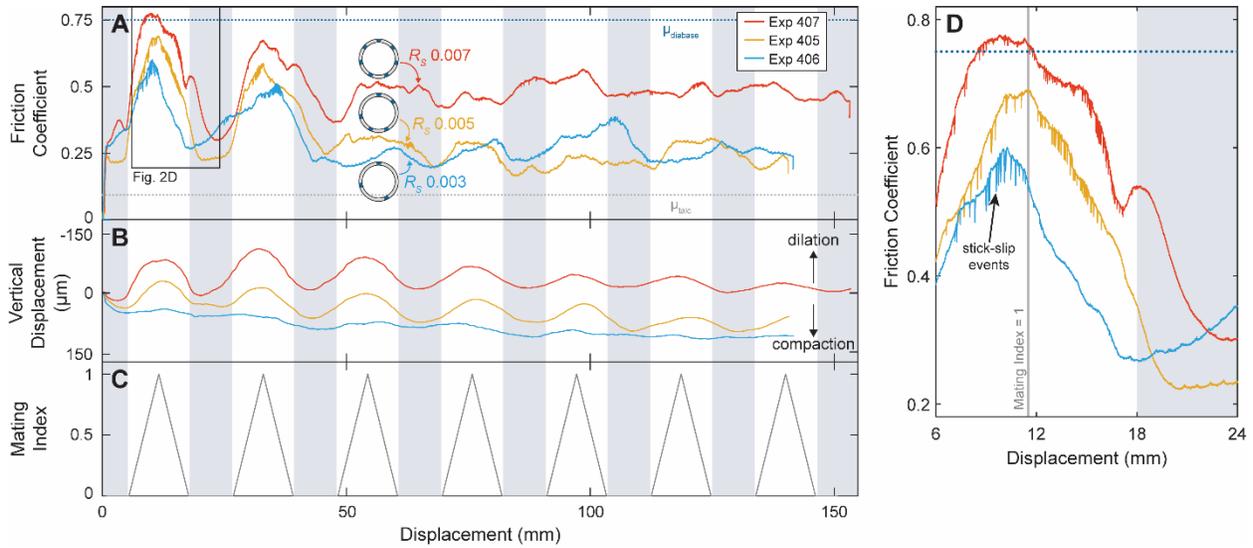
305 slip. B) Lower sample sliding surfaces showing locations of diabase asperities (blue) and talc

306 gouge (gray) for samples with symmetric or asymmetric roughness, R_S or R_A , respectively.

307 Roughness is calculated using the average amplitude to wavelength ratio of asperities on the

308 lower sample. C) Vertically exaggerated (25X) wraparound sections (dashed region in 1A)

309 showing the initial asperity locations in each geometry. $H_A = 150 \mu\text{m}$.



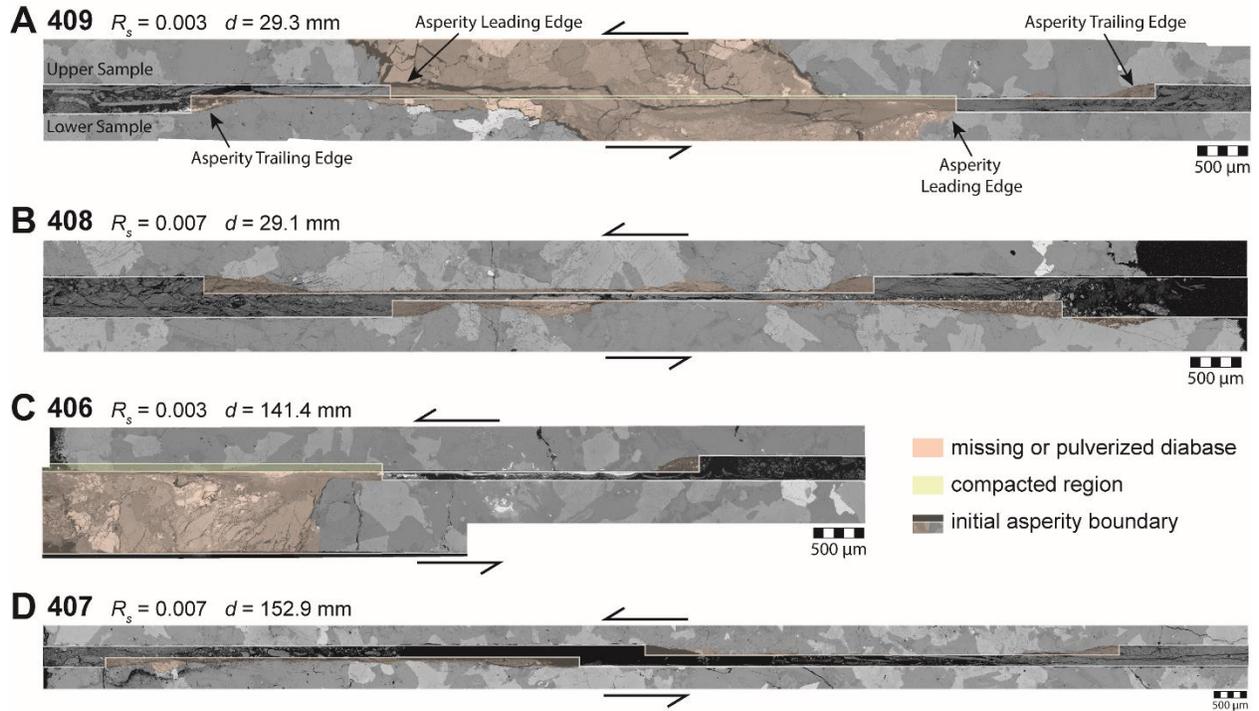
310

311 **Figure 2.** Representative mechanical results from three symmetric roughness experiments: 407312 with a R_s of 0.007 (red), 405 with R_s of 0.005 (yellow), and 406 with R_s of 0.003 (blue). A)

313 Measured coefficient of friction. B) Measured fault-normal displacement. C) Asperity mating

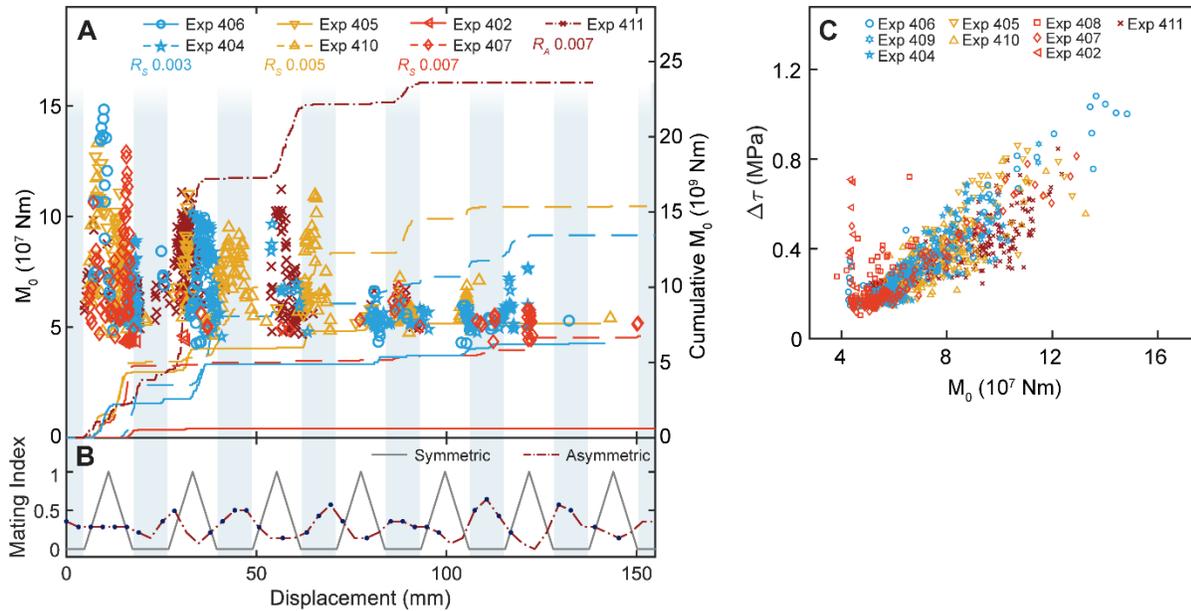
314 index where 1 corresponds to fully mated asperities. D) Close up of μ during and following the

315 first asperity encounter.



316

317 **Figure 3.** Scanning electron microscope images from four experiments. White lines map the
 318 original asperity boundaries. Arrows denote sense of slip for the upper and lower sample blocks.
 319 A and B) Asperities from experiment 409 (A) and 408 (B) after ~ 1.5 asperity encounters. C and
 320 D) Asperities from experiment 406 (C) and 407 (D) after ~ 6.5 and ~ 7 encounters, respectively.



321
 322 **Figure 4.** A) Seismic moments M_0 and cumulative M_0 calculated from StSEs. Two experiments
 323 from each symmetric geometry R_S are plotted alongside one asymmetric geometry R_A
 324 experiment. B) Asperity mating index values. Navy circles mark periods with one or more mated
 325 asperity in the asymmetric geometry. C) Measured shear stress drop $\Delta\tau$ versus M_0 for StSEs in 9
 326 experiments.

327 **¹Supplemental Material.** Additional data, results, apparatus details, and sample details are
 328 available. Please visit <https://doi.org/10.1130/> to access the supplemental material; contact
 329 editing@geosociety.org with any questions.